

# Recognition of food-texture attributes using an in-ear microphone

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- Chewing is one of the main ways of how we perceive food texture
- Some textures are generally perceived as more pleasant and desirable than others <sup>1</sup>
- Several studies show food texture and structure are becoming more important in understanding eating behavior, especially in food intake regulation and weight management <sup>2</sup>

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As a result, automatically recognizing food texture can help

- understand human preference on food selection and help with weight management, as well as improve the nutrition content of diets
- understand consumer preference on food products and design more desirable products

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Food-texture attributes as presented and organized in <sup>3</sup>, and their correspondence with the food-attributes used in this work.

<b>Attributes</b>	<b>Crisp</b>	<b>Wet</b>	<b>Chewy</b>
<i>Attributes related to surface attributes and springiness</i>			
wetness	X	✓	X
adhesiveness to lips	X	X	X
roughness	✓	X	X
self-adhesiveness	X	X	✓
springiness	✓	X	X
<i>Attributes assessed during mastication</i>			
cohesiveness of mass	✓	X	X
moisture absorption	X	✓	X
adhesiveness to teeth	X	X	✓
<i>Attributes assessed during manual manipulation</i>			
manual adhesiveness	X	X	X

<sup>3</sup>Muñoz, A.M.: Development and application of texture reference scales. Journal of Sensory Studies 1(1), 55–83 (1986). <https://doi.org/10.1111/j.1745459X.1986.tb00159.x>

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moisture absorption	✗	✓	✗
adhesiveness to teeth	✗	✗	✓

Multi-label formulation of the food-texture attribute recognition problem.

<b>Label value</b>	<b>Crispiness label</b>	<b>Wetness label</b>	<b>Chewiness label</b>
<b>1</b>	crispy	wet	chewy
<b>0</b>	non-crispy	dry	non-chewy

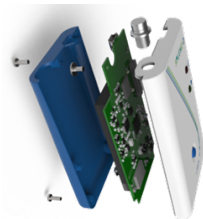
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# The chewing sensor

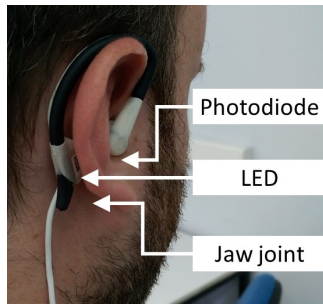
- In-ear microphone (Knowles FG-23329-D65), captures at 48 kHz
- A PPG sensor (New Balance NB439B), not used in this work



**Figure:** The ear-worn device with the microphone and PPG sensor.



**Figure:** The belt-mounted device with 3D accelerometer and data-logger.



**Figure:** PPG placement in ear.

Created within the context of the EU funded SPLENDID project.  
<https://splendid-program.eu/>

Algorithm outline



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### 1 Pre-processing

- 1 Down-sampling (tested 2, 4, 8, 16, and 32 kHz, selected 8 kHz)
- 2 High-pass filtering at 20 Hz

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- 1 Features per chew audio segment, as in Table ( $0.56 \pm 0.15$  s duration)
- 2 Feature standardization:  $f_{\text{norm}}[i] = (f[i] - \mu_i)/\sigma_i$

Table: Audio features.

	Feature	Dimension	Window
1	Energy of log spectral band	9	0.2 s
2	Fractal dimension	1	0.1 s
3	Condition number	1	0.1 s
4	Skewness $m_3((0, 0))$	1	0.1 s
5	Kurtosis $m_4((0, 0, 0))$	1	0.1 s
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### 3 Classification (per chew)

- 1 Binary SVMs, one SVM per food attribute: crispiness, wetness, and chewiness
- 2 RBF kernel
- 3 Parameters  $C$  and  $\gamma$  are selected automatically using Bayesian optimization in a 5-fold cross-validation

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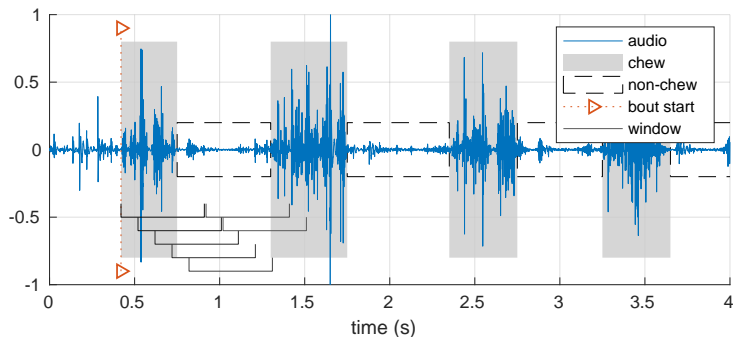
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- 1 Pre-processing
- 2 Feature extraction
  - 1 Same chew-based features
    - ground truth bouts:  $15.22 \pm 10.7$  s duration
    - windows: 0.5 s size, 0.1 s step
  - 2 Feature standardization
- 3 Bag-of-words
  - 1 On the chew-based features
  - 2 Normalized histogram across the chewing bout as the final feature vector
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## Evaluation levels

- Chew-level evaluation
  - for chew-level recognition algorithm
- Bout-level evaluation
  - chew-level recognition algorithm with majority voting
  - chew-level recognition algorithm with majority voting over the  $n$  first chews (of each bout)
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- LOSO: leave one subject out
- LOFTO: leave one food-type out

## Evaluation metrics:

- Accuracy (per food attribute)
- Weight accuracy (per food attribute)

- Collected at Wageningen University, Netherlands, in the context of the EU-funded SPLENDID project
- Recording apparatus: in-ear microphone (Knowles FG-23329-D65) connected via wire to a computer audio interface
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- In total, 21 subjects were enrolled for the data collection trials, however, signals from only 9 could be used in this work due to problems with data acquisition (such as incorrect sensor placement or corrupted audio due to hardware/software malfunction)
- Each subject consumed a variety of food types

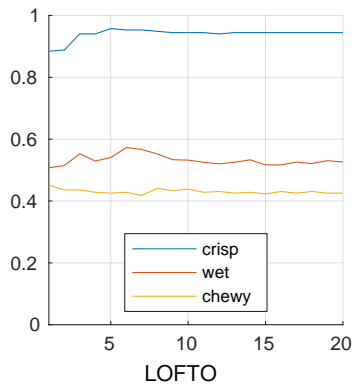
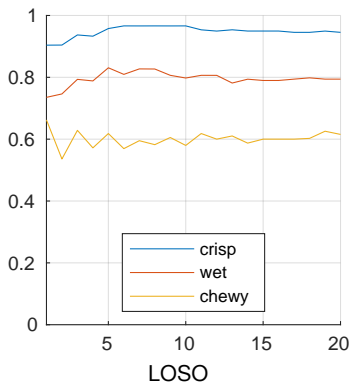
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- Each subject consumed a variety of food types
- Ground truth was manually created based on visual inspection of the audio signals and experimental logs

Table: LOSO results for chew-level recognition.

	Prior	Weighted accuracy
<i>Chew level</i>		
crispy (avg)	0.4707	0.9068
crispy (sum)	0.4666	0.9017
wet (avg)	0.4280	0.7516
wet (sum)	0.4235	0.7503
chewy (avg)	0.1741	0.5994
chewy (sum)	0.1746	0.6212
<i>Majority voting per bout</i>		
crispy (avg)	0.4943	0.9519
crispy (sum)	0.5063	0.9496
wet (avg)	0.4850	0.7978
wet (sum)	0.4937	0.7900
chewy (avg)	0.1666	0.6296
chewy (sum)	0.1632	0.6154

Table: LOFTO results for chew-level recognition.

	<b>Prior</b>	<b>Weighted accuracy</b>
<i>Chew-level</i>		
crispy (sum)	0.4666	0.8987
wet (sum)	0.4235	0.5481
chewy (sum)	0.1746	0.3957
<i>Majority voting per bout</i>		
crispy (sum)	0.4957	0.9446
wet (sum)	0.4829	0.5046
chewy (sum)	0.1667	0.4179



Weighted accuracy for each attribute for the LOSO and the LOFTO experiments.



Table: Results for bout-level recognition.

	Prior	Weighted accuracy
<i>LOSO</i>		
crispy (avg)	0.4967	0.9541
crispy (sum)	0.5084	0.9534
wet (avg)	0.4869	0.7865
wet (sum)	0.4958	0.7900
chewy (avg)	0.1625	0.5200
chewy (sum)	0.1597	0.5238
<i>LOFTO</i>		
crispy (sum)	0.5084	0.9288
wet (sum)	0.4958	0.6422
chewy (sum)	0.1597	0.4970

- Algorithms for automatic recognition of 3 food-texture attributes, namely crispiness, wetness, and chewiness
  - per chew recognition
  - per bout recognition
- Evaluation in LOSO and LOFTO approach
- High recognition for crispiness, promising results for wetness and chewiness

Thank you